Provided by TryEngineering - www.tryengineering.org

Developed by IEEE as part of TryEngineering www.tryengineering.org

Lesson Focus

Develop a robot arm using common materials. Students will explore design, construction, teamwork, and materials selection and use. Note: This lesson plan is designed for classroom use only, with supervision by a teacher familiar with electrical and electronic concepts.



Lesson Synopsis

Participating teams of three or four students are

provided with a bag including the materials listed below. Each team must use the materials to design and build a working robot arm. The robot arm must be at least 18 inches in length and be able to pick up an empty Styrofoam cup. Teams of students must agree on a design for the robot arm and identify what materials will be used. Students will draw a sketch of their agreed upon design prior to construction. Resulting robot arms are then tested and checked for range of motion and satisfaction of the given criteria.

Objectives

- Learn design concepts.
- Learn teamwork.
- Learn problem solving techniques.
- Learn about simple machines.

Anticipated Learner Outcomes

As a result of this activity, students should develop an understanding of:

- design concepts
- teamwork needed in the design process
- impact of technology in manufacturing

Lesson Activities

Students design and build a working robotic arm from a set of everyday items with a goal of having the arm be able to pick up a Styrofoam cup. Working in teams of three or four students, the students explore effective teamwork skills while learning simple robot mechanics.

Alignment to Curriculum Frameworks

See attached curriculum alignment sheet.

Resources/Materials

- 3" wide and approx. 22" long strips of cardboard -- 5 or so
- Binder clips (different sizes) -- 8 or more
- Brads -- @10
- Clothespins -- 6
- Craft sticks --10-15
- Fishing line -- 3-4 feet
- Hangers -- 1 or 2
- Paper clips (diff. Sizes) -- 10-15
- Pencils -- 3-4
- Rubber bands (different sizes) --15
- Tape -- clear and masking (partial rolls should be fine)
- Twine -- 3-4 feet
- Various size scraps of cardboard --10 assorted

Internet Connections

- TryEngineering (www.tryengineering.org)
- Design Your Own Robot (www.mos.org/robot/robot.html)
- FIRST Robotics Competition (www.usfirst.org)
- ITEA Standards for Technological Literacy: Content for the Study of Technology
- (www.iteaconnect.org/TAA)
- NSTA National Science Education Standards (www.nsta.org/standards)
- NCTM Principles and Standards for School Mathematics (http://standards.nctm.org)
- Robot Books (<u>www.robotbooks.com</u>)

Recommended Reading

- Artificial Intelligence: Robotics and Machine Evolution by David Jefferis (ISBN: 0778700461)
- Robotics, Mechatronics, and Artificial Intelligence: Experimental Circuit Blocks for Designers by Newton C. Braga (ISBN: 0750673893)
- Robot Builder's Sourcebook : Over 2,500 Sources for Robot Parts by Gordon McComb (ISBN: 0071406859)
- Robots (Fast Forward) by Mark Bergin (ISBN: 0531146162)

Optional Writing Activity

• Write an essay (or paragraph depending on age) about how the invention of robots and robotics has impacted manufacturing.

References

Ralph D. Painter and other volunteers - Florida West Coast USA Section of IEEE URL: http://ewh.ieee.org/r3/floridawc

Developed by IEEE as part of TryEngineering www.tryengineering.org

MESA Day Prosthetic Arm Curriculum

For Teachers:

Alignment to Curriculum Frameworks

Note: All Lesson Plans in this series are aligned to the National Science Education Standards which were produced by the National Research Council and endorsed by the National Science Teachers Association, and if applicable, also to the International Technology Education Association's Standards for Technological Literacy or the National Council of Teachers of Mathematics' Principles and Standards for School Mathematics.

National Science Education Standards Grades 5-8 (ages 10 - 14) CONTENT STANDARD B: Physical Science

As a result of their activities, all students should develop an understanding of

- Motions and forces
- Transfer of energy

National Science Education Standards Grades 9-12 (ages 14 - 18) CONTENT STANDARD B: Physical Science

As a result of their activities, all students should develop understanding of

- Motions and forces
- Interactions of energy and matter

CONTENT STANDARD E: Science and Technology

As a result of activities, all students should develop

- Abilities of technological design
- Understandings about science and technology

Standards for Technological Literacy - All Ages

The Nature of Technology

• Standard 3: Students will develop an understanding of the relationships among technologies and the connections between technology and other fields of study.

Technology and Society

• Standard 7: Students will develop an understanding of the influence of technology on history.

Design

- Standard 9: Students will develop an understanding of engineering design.
- Standard 10: Students will develop an understanding of the role of troubleshooting, research and development, invention and innovation, and experimentation in problem solving.

Abilities for a Technological World

• Standard 11: Students will develop abilities to apply the design process.

The Designed World

• Standard 19: Students will develop an understanding of and be able to select and use manufacturing technologies.

Robot Arm Developed by IEEE as part of TryEngineering www.tryengineering.org

For Teachers:

Teacher Resources

Divide your class into teams of three or four students, and provide student handout (attached). Students are then instructed to examine the materials provided (see list below) and to work as a team to design and build a robot arm out of the materials. The robot arm must be at least 18 inches in length and be able to pick up an empty Styrofoam cup. Teams of students must agree on a design for the robot arm and identify what materials will be used. Students should draw a sketch of their agreed upon design prior to construction.

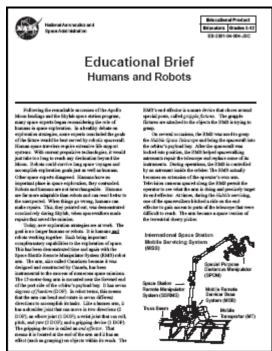
Explain that teamwork, trial, and error are part of the design process. There is no "right" answer to the problem - each team's creativity will likely generate an arm that is unique from the others designed in your class.

Resources/Materials

- 3" wide and approx. 22" long strips of cardboard-- 5 or so
- Binder clips (different sizes)-- 8 or more
- Brads-- @10
- Clothespins-- 6
- Craft sticks--10-15
- Fishing line-- 3-4 feet
- Hangers-- 1 or 2
- Paper clips (diff. Sizes)-- 10-15
- Pencils-- 3-4
- Rubber bands (different sizes)--15
- Tape-- clear and masking (partial rolls should be fine)
- Twine-- 3-4 feet
- Various size scraps of cardboard--10 assorted

Extension Ideas

"Humans and Robots," a NASA educational brief which is attached, describes the robotics features on the International Space Station. The brief's classroom activity is about making and using an ISS grapple fixture known as an end effector. The PDF file is also available at http://spacelink.nasa.gov.



Robot Arm Developed by IEEE as part of TryEngineering www.tryengineering.org

MESA Day Prosthetic Arm Curriculum

Student Worksheet :

How To Build Your Own Robot Arm

You are a member of a team of three or four students, all working together to design and build a robot arm out of the following materials which are provided to you. The robot arm must be at least 18 inches in length and be able to pick up an empty Styrofoam cup. Your team must agree on a design for the robot arm and identify what materials will be used. Your team should draw a sketch of their agreed upon design prior to construction.

Part of the teamwork process is sharing ideas and determining which design your team will go with. Trial and error are part of the design process. There is no "right" answer to the problem - your team's creativity will likely generate an arm that is unique from the others designed in your class.

Resources/Materials

- 3" wide and approx. 22" long strips of cardboard-- 5 or so
- Binder clips (different sizes)-- 8 or more
- Brads-- @10
- Clothespins-- 6
- Craft sticks--10-15
- Fishing line-- 3-4 feet
- Hangers-- 1 or 2
- Paper clips (diff. Sizes)-- 10-15
- Pencils-- 3-4
- Rubber bands (different sizes)--15
- Tape-- clear and masking (partial rolls should be fine)
- Twine-- 3-4 feet
- Various size scraps of cardboard--10 assorted

Developed by IEEE as part of TryEngineering www.tryengineering.org

Student Worksheet: Robot Arm Exercise Questions

- Did you use all the materials provided to you? Why, or why not?
- Which item was most critical to your robot arm design?
- How did working as a team help in the design process?
- Were there any drawbacks to designing as a team?
- What did you learn from the designs developed by other teams?
- Name three industries that make use of robots in manufacturing:

Robot Arm Developed by IEEE as part of TryEngineering www.tryengineering.org

MESA Day Prosthetic Arm Curriculum These materials are for the internal use of California MESA staff and teachers only and should not be forwarded or used outside of MESA.

References

Information for this curriculum was taken from the following websites:

- "Arm." Encyclopædia Britannica. 2009. Encyclopædia Britannica Online. 16 Jul. 2009 http://www.britannica.com/EBchecked/topic/35010/arm.
- Chai, Huei-Ming, *Kinesiology*. 2 January 2005. School of Physical Therapy, National Taiwan Univ. 13 July 2009. http://www.pt.ntu.edu.tw/hmchai/Kines04/KINoutline.htm.
- Eaton, Charles MD. *E-Hand.com: The Electronic Textbook of Hand Surgery*. The Hand Center. 15 July 2009. http://www.eatonhand.com/index.htm.
- Engineering Your Future. 29 July 2009. http://www.futuresinengineering.com/.
- Glenbrook South Physics Teachers. *Glenbrook South Physics Home Page* (curriculum and lessons). 22 July 2009. http://www.glenbrook.k12.il.us/GBSSCI/PHYS/phys.html.
- InnerBody: Guide to Human Anatomy Online. 10 July 2009. http://www.innerbody.com.
- Whitaker, Robert MD. Instant Anatomy. 10 July 2009. http://www.instantanatomy.net.
- Levangie, Pamela and Norkin, Cynthia. *Joint Structure and Function: A Comprehensive Analysis.* 4th Edition. Philadelphia, PA: F.A. Davis Company, 2005.
- National Skeletal Muscle Research Center, UC San Diego, http://muscle.ucsd.edu/NSMRC/home.shtml.
- Norman, Wesley, PhD, DSc. *The Anatomy Lesson*. 13 July 2009. http://home.comcast.net/~wnor/homepage.htm
- Ozkaya, Nihat and Nordin, Margareta. *Fundamentals of Biomechanics: Equilibrium, Motion, and Deformation.* New York: Springer-Verlag, 1999.
- Pediatric Orthopaedics. 15 July 2009. http://www.pediatric-orthopedics.com/index.html
- The Physics Classroom. http://www.physicsclassroom.com
- Richards, Lorie and Loudon, Janice. *Hand Kinesiology*. University of Kansas Medical Center, school of Allied Health, Occupational and Physical Theraphy Education, http://classes.kumc.edu/sah/resources/handkines/kines2.html.
- *Try Engineering*. http://www.tryengineering.org.
- *Understanding Arm Anatomy and Function*. Healthline Network. http://www.healthline.com/hlbook/strt-understanding-arm-anatomy-and-function
- Wikipedia. http://en.wikipedia.org.
- Zhang, Yi, *Introduction to Mechanisms*. Carnegie Mellon University. http://www.cs.cmu.edu/~rapidproto/mechanisms/chpt4.html

MESA Day Prosthetic Arm Curriculum